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FORECASTING FOR FINANCIAL
RISK MANAGEMENT?

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ABSTRACT

It depends. If volatility fluctuates in a forecastable way, then volatility forecasts are useful for risk management; hence the interest in volatility forecastability in the risk management literature. Volatility forecastability, however, varies with horizon, and different horizons are relevant in different applications. Moreover, existing assessments of volatility forecastability are plagued by the fact that they are *joint* assessments of volatility forecastability and an assumed model, and the results vary not only with the horizon, but also with the assumed model. To address this problem, we develop a model-free procedure for assessing volatility forecastability across horizons. Perhaps surprisingly, we find that volatility forecastability decays quickly with horizon. Volatility forecastability, although clearly of relevance for risk management at the short horizons relevant for, say, trading desk management, may not be important for risk management more generally.

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1. Introduction

Many private-sector firms engage in risk management. In the financial services industry, in particular, both interest and capability in risk management are expanding rapidly. Particularly active areas include investment banking, commercial banking, and insurance.¹ Interest has similarly escalated on the regulatory side, as governments around the world seek to impose risk-based capital adequacy standards.² It is not an exaggeration to say that risk management has emerged as a major industry in the last ten years, with outlets such as *Risk Magazine* chronicling the development and bridging industry and academics.

At first pass, private-sector interest in risk management seems curious. Modigliani and Miller (1958) taught us long ago that the value of a firm is independent of its risk structure; firms should simply maximize expected profits, regardless of the risk entailed; holders of securities can achieve risk transfers via appropriate portfolio allocations. It is clear, however, that the strict conditions required for the Modigliani-Miller theorem are routinely violated in practice.³ In particular, capital market imperfections, such as taxes and costs of financial distress, cause the theorem to fail and create a role for risk management. Ultimately, firms optimize nonlinear objective functions that are much more complicated than simple expected profits.

The rapid expansion in risk management interest and capability is driven by several factors. One obvious factor is the growth in financial derivative markets and products, and the exciting

¹ See Santomero (1995, 1997) and Babbel and Santomero (1997).

² See, for example, Kupiec and O'Brien (1995).

³ Such imperfections motivate much of the recent risk management literature. See, for example, Froot, Scharfstein, and Stein (1993, 1994) and Oldfield and Santomero (1997).

capabilities for risk management that they provide. A second key factor, very much relevant for this paper, is the revolution in modeling and forecasting volatility that began in academics nearly two decades ago (Engle, 1982). The maturation of the literature on volatility modeling, together with concomitant advances in computation and simulation, has fueled the development of powerful risk-management methods and software. The key insight is that if volatility fluctuates in a forecastable way, then good volatility forecasts can improve financial risk management, which effectively amounts to forecasting the risk associated with holding potentially complicated nonlinear portfolios.

The risk of holding such a portfolio of course depends on the holding period, or horizon. But what *is* the relevant horizon for risk management? This obvious question has no obvious answer. Perusal of the industry literature reveals widespread discussion of the importance of the horizon, disagreement as to the relevant horizon, and interestingly, an emerging recognition that fairly long horizons are relevant in many applications. Smithson and Minton (1996, p. 39), for example, note that “Nearly all risk managers believe the one-day ... approach is valid for trading purposes. However, they disagree on the appropriate holding period for the long-term solvency of the institution.” Chew (1994, p. 65) elaborates, asking whether “...any ... short holding period ... is relevant for risk controllers...” McNew (1996, p. 56) makes a precise recommendation, arguing that “If corporate America were to apply [modern financial risk management techniques] to its asset/liability risk management problem, it is probable that the time horizon would not be less than one quarter and could be significantly longer.”

The upshot, of course, is that there is no one “relevant” horizon, so that thought must be given to the relevant horizon on an application-by-application basis. The relevant horizon will, in

particular, likely vary with position in the firm (e.g., trading desk vs. CFO), motivation (e.g., private vs. regulatory), asset class (e.g., equity vs. fixed income), and industry (e.g., banking vs. insurance). These considerations lead to an important insight: although very short horizons may be appropriate for certain tasks, such as managing the risk of a trading desk, much longer horizons may be relevant in other contexts

There is little doubt that volatility *is* forecastable on a very high frequency basis, such as hourly or daily.⁴ Interestingly, however, much less is known about volatility forecastability at longer horizons, and more generally, the pattern and speed of decay in volatility forecastability as we move from short to long horizons. Thus, open and key questions remain for risk management at all but the shortest horizons. How forecastable is volatility at various horizons? With what speed and pattern does forecastability decay as horizon lengthens? Are the recent advances in volatility modeling and forecasting, such as GARCH, stochastic volatility and related approaches, useful for risk management at longer horizons, or is longer-horizon volatility approximately constant?

One approach to answering these questions involves estimating the path of short-horizon volatility and using it to infer the properties of long-horizon volatility. The simplest implementation of this temporal aggregation idea is the popular industry practice of “scaling up” high-frequency volatility estimates to get a low-frequency volatility estimate (e.g., converting a 1-day return standard deviation to a 30-day return standard deviation by multiplying by $\sqrt{30}$). Unfortunately, except under restrictive and routinely-violated conditions, scaling is misleading and tends to produce spurious magnification of volatility fluctuations with horizon, as shown by

⁴ See, for example, Bollerslev, Chou and Kroner (1992).

Diebold et al. (1998).

A more appropriate temporal aggregation strategy is to fit a model to the high-frequency data and, conditional upon the truth of the fitted model, use it to infer the properties of the low-frequency data. Drost and Nijman (1993), for example, provide temporal aggregation formulae for the weak GARCH(1,1) process. That approach has at least two drawbacks, however. First, the aggregation formulae assume the truth of the fitted model, when in fact the fitted model is simply an approximation, and the best approximation to h-day volatility dynamics is not likely to be what one gets by aggregating the best approximation (let alone a mediocre approximation) to 1-day volatility dynamics.⁵ Second, temporal aggregation formulae are presently available only for restrictive classes of models; the literature has progressed little since Drost and Nijman.

An alternative strategy is simply to fit volatility models directly to returns at various horizons of interest, thereby avoiding temporal aggregation entirely. The idea of working directly at the horizons of interest is a good one, but unfortunately, different families of parametric volatility models may produce different conclusions about forecastability, as in Hsieh (1993). What we really want, then, is a way to assess volatility forecastability directly from observed returns at various horizons, without conditioning on an assumed model. In this paper, we propose a method for doing so, and we use it to assess patterns of volatility forecastability in equity, foreign exchange, and bond markets, with surprising results. We proceed as follows. In section 2, we describe in detail our framework for model-free evaluation of volatility forecastability, and then in section 3 we use our methods to assess the volatility forecastability for returns on four major equity indexes, four major dollar exchange rates, and the U.S. 10-year Treasury bond, at

⁵ See Findley (1983), Weiss (1991), and Tiao and Tsay (1993).

horizons ranging from one through twenty trading days. In section 4 we offer concluding remarks and directions for future research.

2. Methods

In this section we describe and assemble the tools necessary for a workable strategy of model-free assessment of volatility forecastability in risk management contexts. First we sketch the intuition and give a precise statement of our methods. In particular, we show that recently-developed tests of conditional calibration of interval forecasts can be used to provide model-free assessments of volatility forecastability. Next, we develop a formal test of volatility forecastability. Finally, we propose a natural and complementary measure of the *strength* of volatility forecastability, and we sketch a strategy for its estimation and inference.

Model-Free Assessment of Volatility Forecastability

Our strategy for assessing volatility forecastability is intimately connected to assessing the adequacy of interval forecasts. Christoffersen (1998) develops a framework for evaluating the adequacy interval forecasts, and our methods build directly on his. Suppose that we observe a sample path $\{y_t\}_{t=1}^T$ of the time series y_t and a corresponding sequence of 1-step-ahead interval forecasts, $\{(L_{t|t-1}(p), U_{t|t-1}(p))\}_{t=1}^T$, where $L_{t|t-1}(p)$ and $U_{t|t-1}(p)$ denote the lower and upper limits of the interval forecast for time t made at time $t-1$ with desired coverage probability p . We define the hit sequence I_t as

$$I_t = \begin{cases} 1, & \text{if } y_t \in [L_{t|t-1}(p), U_{t|t-1}(p)] \\ 0, & \text{otherwise,} \end{cases}$$

for $t = 1, 2, \dots, T$. We say that a sequence of interval forecasts has correct *unconditional*

coverage if $E[I_t] = p$ for all t ; that is the standard notion of “correct coverage.”

Correct unconditional coverage is appropriately viewed as a necessary condition for adequacy of an interval forecast. It is not sufficient, however. In particular, in the presence of conditional heteroskedasticity, it is important to check for adequacy of conditional coverage, which is a stronger concept. We say that a sequence of interval forecasts has *correct conditional coverage with respect to an information set* Ω_{t-1} if $E[I_t | \Omega_{t-1}] = p$ for all t . Correct conditional coverage trivially implies correct unconditional coverage; correct unconditional coverage is simply correct conditional coverage with respect to an empty information set. Christoffersen (1998) shows that if $\Omega_{t-1} = \{I_{t-1}, I_{t-2}, \dots, I_1\}$, then correct conditional coverage is equivalent to $\{I_t\} \stackrel{iid}{\sim} \text{Bernoulli}(p)$, which can readily be tested.

Having given some background on interval forecast evaluation, now let us proceed to our ultimate goal, development of tools for model-free assessment of volatility forecastability. Assume that the process y whose volatility forecastability we want to assess is covariance stationary, and without loss of generality assume a zero mean. Pick a constant interval symmetric around zero, $[-c, c]$.⁶ The key insight is that although the interval $[-c, c]$ is *unconditionally* correctly calibrated at *some* unknown confidence level, p , it is not *conditionally* correctly calibrated if volatility is forecastable. More precisely, if we measure volatility by the conditional variance, and we know that if the conditional variance adapts to the evolving information set given by $\{y_{t-1}, y_{t-2}, \dots, y_1\}$, then a fixed-width confidence interval could not be correctly conditionally calibrated, because it fails to widen when the conditional variance rises and narrow

⁶ Any value of c could be chosen, but typical values would be in range of one or two unconditional standard deviations of y . One could also use an asymmetric interval, but we shall not pursue that idea here.

when the conditional variance falls.

The implied strategy for evaluating volatility forecastability is obvious: we know that confidence intervals of the form $[-c, c]$ are correctly unconditionally calibrated at some level, but we don't know whether they are correctly conditionally calibrated, which is to say we don't know whether volatility is forecastable. If the $[-c, c]$ intervals are not only correctly *unconditionally* calibrated, but also correctly *conditionally* calibrated, then volatility is not forecastable in our terminology, and the hit sequence is iid.

Assessing Independence of the Hit Sequence: A Runs Test

We have seen that non-forecastability of volatility corresponds to an iid hit sequence; we now describe a convenient and powerful model-free procedure for testing independence of the hit sequence. Define a run as a string of consecutive zeros or ones in the hit sequence.⁷ Let r be the number of runs, and let n_0 and n_1 be the total number of zeros and ones in the sequence. Then $T=n_0+n_1$, and if R is the maximum number of runs possible, then

$$R = \begin{cases} 2 \min\{n_0, n_1\}, & \text{if } n_0 = n_1 \\ 2 \min\{n_0, n_1\} + 1, & \text{otherwise.} \end{cases}$$

Under the null hypothesis that $\{I_t\}_{t=1}^T$ is a random sequence, the distribution of the number of runs, r , given n_1 and n_0 , is (for $\min\{n_0, n_1\} > 0$)

$$\Pr(r|n_0, n_1) = \frac{f_r}{\binom{T}{n_0}}, \text{ for } r = 2, 3, \dots, R,$$

⁷ For example, the sequence $\{I_t\}_{t=1}^{10} = \{0,0,1,1,1,0,1,0,0,0\}$ has five runs.

where

$$f_{r=2s} = 2 \binom{n_0-1}{s-1} \binom{n_1-1}{s-1} \text{ and } f_{r=2s+1} = \binom{n_0-1}{s} \binom{n_1-1}{s-1} \binom{n_0-1}{s-1} \binom{n_1-1}{s} = \frac{f_{2s}(T-2s)}{2s}.$$

This distributional result provides a handy test of independence of the hit sequence, notice that it does not depend on the nominal coverage of the intervals, p .⁸ Moreover, the runs test is exact, and it is uniformly most powerful against a first-order Markov alternative.⁹

Measuring Volatility Forecastability: Markov Transition Matrix Eigenvalues

We now define a forecastability measure based on a first-order Markov alternative, which therefore naturally complements the runs test of independence. Let the hit sequence be first-order Markov with arbitrary transition probability matrix

$$\Pi = \begin{bmatrix} 1-\pi_{01} & \pi_{01} \\ 1-\pi_{11} & \pi_{11} \end{bmatrix},$$

where $\pi_{ij} = \Pr(I_t = j | I_{t-1} = i)$. The eigenvalues are solutions to the equation

$$\left| \lambda \mathbf{I} - \begin{bmatrix} 1-\pi_{01} & \pi_{01} \\ 1-\pi_{11} & \pi_{11} \end{bmatrix} \right| = 0 ;$$

the first eigenvalue is necessarily unity and therefore conveys no information regarding the forecastability of the hit sequence, and the second eigenvalue is simply $S \equiv \pi_{11} - \pi_{01}$. S is a natural

⁸ The runs test of randomness of a binary variable traces at least to David (1947).

⁹ See Lehmann (1986) for details.

persistence measure; note that under independence $\pi_{01} = \pi_{11}$, so $S=0$, and conversely, under strong positive persistence π_{11} will be much larger than π_{01} , so S will be large.¹⁰

S has an alternative and intuitive motivation: it is the first-order serial correlation coefficient of the hit sequence. To see this, we note that¹¹

$$E[I_t] = p = p\pi_{11} + (1-p)\pi_{01} = \frac{\pi_{01}}{1 + \pi_{01} - \pi_{11}}$$

$$\text{Var}[I_t] = p(1-p) = \frac{\pi_{01}(1 - \pi_{11})}{1 + \pi_{01} - \pi_{11}}$$

$$\text{Cov}(I_t, I_{t-1}) = E[I_t I_{t-1}] - E^2[I_t] = p\pi_{11} - p^2 = p(\pi_{11} - p).$$

Then we form the correlation coefficient and use some algebra to obtain

$$\text{Corr}(I_t, I_{t-1}) = \frac{\pi_{11} - p}{1 - p} = \frac{\pi_{11}(1 + \pi_{01} - \pi_{11}) - \pi_{01}}{1 - \pi_{11}} = \pi_{11} - \pi_{01} = S.$$

Thus, just as in the familiar AR(1) case for which the root of the autoregressive lag-operator polynomial is the first-order serial correlation coefficient, so too in the first-order Markov case is

¹⁰ Analogous use of eigenvalues as mobility measures has been suggested by Shorrocks (1978) and Sommers and Conlisk (1979).

¹¹ To evaluate the covariance, use the fact that $E[I_t I_{t-1}] = \Pr(I_t=1 \cap I_{t-1}=1) = p\pi_{11}$.

the (non-trivial) eigenroot.¹²

Estimating the Markov Model

The discussion of forecastability measurement has thus far been in population; in practice, of course, one must estimate the relevant Markov models. Maximum-likelihood estimation is particularly simple. For a hit sequence $\{I_1, \dots, I_T\}$, the likelihood function is immediately¹³

$$L(\pi_{01}, \pi_{11}; I_1, I_2, \dots, I_T) = (1 - \pi_{01})^{n_{00}} \pi_{01}^{n_{01}} (1 - \pi_{11})^{n_{10}} \pi_{11}^{n_{11}},$$

where n_{ij} is the number of observations with value i followed by j . The maximum likelihood

estimators of π_{01} and π_{11} are therefore $\hat{\pi}_{01} = \frac{n_{01}}{n_{00} + n_{01}}$ and $\hat{\pi}_{11} = \frac{n_{11}}{n_{10} + n_{11}}$. By Slutsky's theorem,

the maximum likelihood estimate of the non-unit eigenvalue is then $\hat{S} = \hat{\pi}_{11} - \hat{\pi}_{01}$.

Unlike the exact finite-sample theory available for the runs test of independence, the theory associated with maximum-likelihood estimation of the transition matrix eigenvalue is only asymptotic. Thus, in an attempt to tailor our inference to precise sample sizes relevant for the application at hand, we use simulation methods to assess the significance of our eigenvalue estimates. In particular, for any returns series, we:

(a) De-mean the returns series

(b) Compute the hit sequence relative to the constant $\pm c$ interval, and then compute the estimate of p , \hat{p} , and the estimate of S , \hat{S} .

¹² See also Hamilton (1994, p. 687).

¹³ As is standard, we form the likelihood conditional on the first observation, I_1 .

(c) Use \hat{p} and the relevant sample size T to:

(c1) generate $m = 1, \dots, M$ samples of iid Bernoulli(\hat{p}) pseudo-data

(c2) compute \hat{S}_m

(c3) compute the 95 percent confidence interval for \hat{S}_m and plot it together with \hat{S} computed in (b).

3. Volatility Forecastability in Financial Asset Markets

Armed with the tools introduced above, we now proceed to measure volatility forecastability in global foreign exchange, stock and bond markets. We examine asset return volatility forecastability as a function of the horizon over which the returns are computed, beginning with daily returns and then proceeding through non-overlapping h -day returns, $h = 1, 2, 3, \dots, 20$.¹⁴

Because the unconditional volatility of all asset returns rises with the aggregation level, it is natural and appropriate to let the width of our fixed $[-c, c]$ intervals change with the aggregation level. We do so throughout; in fact, we use $\pm 2\hat{\sigma}$ intervals to compute our hit sequences. This yields unconditional coverage in the range of 90 to 95 percent, which makes for a nice parallel to the value-at-risk (VaR) literature, which typically focuses on VaR in the range of 1 to 10 percent.

Equity and Foreign Exchange Markets

We begin by examining stock and exchange rate returns.¹⁵ We examine returns on four

¹⁴ Use of non-overlapping returns eliminates the need to account for the dependence induced by overlapping observations.

¹⁵ For reasons that will be made clear, bond returns are better analyzed separately, so we postpone their analysis until later in the paper.

broad-based stock indexes: the U.S. S&P 500, the German DAX, the U.K. FTSE, and the Japanese TPX. We examine returns on four dollar exchange rates: the German Mark, British Pound, Japanese Yen and French Franc. The sample starts on January 1, 1973 and ends on May 1, 1997, resulting in 6350 daily observations for each return series.¹⁶

Let us first discuss the runs tests. In Figure 1 we show the finite-sample P-values of the runs tests of independence of the hit, as a function of the horizon. It is clear that, for each equity index, the P-values tend to increase with the horizon, although the specifics differ somewhat depending on the particular index examined. As a rough rule of thumb, we summarize the results as saying that for horizons of less than ten trading days we tend to reject independence, which is to say that equity return volatility is significantly forecastable, and conversely for horizons greater than ten days. Figure 2 reveals identical patterns for exchange rates.

One difficulty with the runs test framework is its exclusive emphasis on *testing* for volatility forecastability, as opposed to *measuring* the strength of volatility forecastability. Presumably some volatility forecastability exists even at the longer horizons, and the runs test would detect it if the sample size were larger. But again, interest focuses not on the *existence* of volatility forecastability, but rather on its *strength*. Hence we now turn to the estimated transition matrix eigenvalues, which measure the strength of volatility forecastability and are therefore more directly aligned with our ultimate concerns.

¹⁶ The equity and foreign exchange data are from Datastream International. Equity prices are official local closing prices provided by the local exchanges; we compute equity returns as logarithmic differences of those prices. Foreign exchange rates are London bid/ask average closing quotes; we compute foreign exchange returns as logarithmic differences of those exchange rates. The bond yields are from Bloomberg Financial Services; they are New York bid/ask average closing quotes.

We show the estimated transition matrix eigenvalues along with their simulated finite-sample 95% confidence intervals, again as a function of horizon, in Figures 3 and 4. A consistent pattern emerges across all equities and exchange rates: at very short horizons, typically from one to ten trading days, the eigenvalues are significantly positive, but they decrease quickly, and approximately monotonically, with the horizon. By the time one reaches 10-day returns -- and often substantially before -- the estimated eigenvalues are small and statistically insignificant, indicating that volatility forecastability has vanished.

Bond Markets

We report results for bonds separately for three reasons; the first two are linked to a priori concerns, and the third concerns the different nature of the results. First, historical bond market data typically contain only the annual yield, not the price, and it is not possible to calculate exact returns on a bond from yield alone. Thus to compute bond returns we are forced to make a potentially inaccurate approximation, which is not required to compute equity and exchange returns. Second, the available historical samples of bond yield data are much more limited; in fact, we analyze the returns of only one bond, the U.S. 10-year Treasury. Third, as we shall show, patterns of bond-market volatility forecastability are (perhaps suspiciously) different from those in equity and foreign exchange markets and are therefore usefully discussed separately.

Let us begin with a yield-based approximation to a bond's return. Recall that the price of a bond that pays a coupon rate of C every period and \$1 at maturity after n periods is

$$P_{\text{cnt}} = C \sum_{i=1}^n \frac{1}{(1+Y_{\text{cnt}})^i} + \frac{1}{(1+Y_{\text{cnt}})^n},$$

where Y_{cnt} is the yield per period. Also recall that Macaulay's duration is defined by

$$D_{cnt} = \frac{\sum_{i=1}^n \frac{iC}{(1+Y_{cnt})^i} + \frac{n}{(1+Y_{cnt})^n}}{P_{cnt}},$$

which can also be written as¹⁷

$$D_{cnt} = - \frac{\Delta P_{cnt}}{\Delta(1+Y_{cnt})} \frac{1+Y_{cnt}}{P_{cnt}}.$$

Assume that the coupon rate is close to the yield, $C \approx Y_{cnt}$, in which case the bond will be priced near par, $P_{cnt} \approx 1$, resulting in the approximate duration¹⁸

$$D_{cnt} \approx \frac{1 - (1+Y_{cnt})^{-n}}{1 - (1+Y_{cnt})^{-1}}.$$

Finally, use the fact that $\Delta(1+Y_{cnt}) = \Delta Y_{cnt}$ to rewrite the exact duration formula as

$$\frac{\Delta P_{cnt}}{P_{cnt}} = - \frac{D_{cnt} \Delta Y_{cnt}}{1+Y_{cnt}},$$

which when combined with the approximate duration formula yields an approximation for returns as a function only of yield and time to maturity,

¹⁷ See, for example, Campbell, Lo and MacKinlay (1997, p. 403).

¹⁸ This approximate duration formula can also be derived as an exact duration in Campbell's approximate log-linear model. See Campbell, Lo and MacKinlay (1997, p. 408).

$$\frac{\Delta P_{cnt}}{P_{cnt}} \approx - \frac{\Delta Y_{cnt}}{1 + Y_{cnt}} \left(\frac{1 - (1 + Y_{cnt})^{-n}}{1 - (1 + Y_{cnt})^{-1}} \right).$$

Having arrived at a workable approximation to bond returns, we now examine the forecastability of bond return volatility. Limited availability of historical daily international bond yield data forces us to focus exclusively on the 10-year U.S. Treasury bond. As before, the daily sample starts on January 1, 1973 and ends on May 1, 1997. The estimated Markov transition matrix eigenvalues, which appear in Figure 5, indicate substantially more volatility forecastability than in the equity or foreign exchange markets, with some forecastability as far ahead, say, as 15-20 trading days.¹⁹

It is hard to determine whether the apparently greater bond market volatility predictability is real, or whether it is an artifact. We have already mentioned that it could be an artifact of the approximation necessary to calculate bond returns. It could also be an artifact of the structural break in Federal Reserve policy around 1980, which produces the spurious appearance of high volatility forecastability if not properly accounted for, as suggested by Diebold (1986) and verified by Lamoureux and Lastrapes (1990) and Hamilton and Susmel (1994). At any rate, our finding that volatility is more forecastable in bond markets than elsewhere is consistent with existing evidence, including Engle, Lilien, and Robins (1987) and Andersen and Lund (1997).²⁰

4. Concluding Remarks and Directions for Future Research

Interpretation of our Results

¹⁹ The runs test P-values, which we omit to save space, tell the same story.

²⁰ See also the survey by Bollerslev, Chou and Kroner (1992).

If volatility is forecastable at the horizons of interest, then volatility forecasts are relevant for risk management. But our results indicate that if the horizon of interest is more than ten or twenty days, depending on the asset class, then volatility forecasts may not be of much importance. Our results clash with the assumptions embedded in popular risk management paradigms, which effectively assume highly forecastable volatility. J.P. Morgan's RiskMetrics, for example, is based on forecasts produced by exponentially smoothing squared returns, which are optimal only in the case of *integrated* volatility dynamics. Our results are, however, consistent with academic studies such as West and Cho (1995), who find that volatility forecasts are not of much importance in foreign exchange markets beyond a 5-day horizon.²¹

We would argue, moreover, that our results are consistent with those of a number of seemingly-conflicting recent academic studies, which fall into two groups. The first group documents slow decay in long-lag autocorrelations of squared or absolute returns, which indicates long-memory volatility dynamics and would seem to indicate forecastability of volatility at very long horizons (e.g., Andersen and Bollerslev, 1997). But that literature tends to work with very high-frequency data -- typically 5-minute returns -- and although long memory in 5-minute returns may well indicate that volatility is highly forecastable many steps into the future, perhaps 100 steps or even 1000 steps, it does not necessarily indicate forecastability beyond ten or twenty days. 1000 5-minute steps, for example, are just more than three days; even 5000 5-minute steps are just more than 17 days.

The second group refutes evidence of the sort provided by Jorion (1995), which seems to

²¹ The methods of West and Cho (1995), moreover, differ substantially from ours and therefore lend independent confirmation.

indicate that ARCH models provide poor volatility forecasts, by showing that volatility is much more forecastable when an appropriate measure of realized volatility is used (e.g., Andersen and Bollerslev, 1998). That literature, however, focuses on 1-day-ahead volatility forecasts, and certainly we agree that *short*-horizon volatility is highly forecastable. Our analysis, in contrast, focuses on longer-horizon volatility.

What Next?

We see two particularly interesting directions for future research. The first involves the use of economic, as opposed to statistical, metrics of volatility forecastability. Within the risk management perspective, for example, one might try to assess whether use of volatility forecasts improves the accuracy of calculated VaR at various horizons. One could also examine the usefulness of long-horizon volatility forecasts from other perspectives, including asset allocation, as in West, Edison and Cho (1993) and derivatives pricing, as in Engle et al. (1993).

The second direction for future research involves addressing the obvious question that emerges from our work: if volatility dynamics are not important for long-horizon risk management, then what *is* important? It seems to us that all models miss the really big movements such as the U.S. crash of 1987, and ultimately the really big movements are the most important for risk management. This suggests the desirability of directly modeling the extreme tails of return densities, a task facilitated by recent advances in extreme value theory surveyed by Embrechts, Klüppelberg and Mikosch (1997) and applied to financial risk management by Danielsson and de Vries (1997). Preliminary ruminations along those lines appear in Diebold, Schuermann and Stroughair (1998).

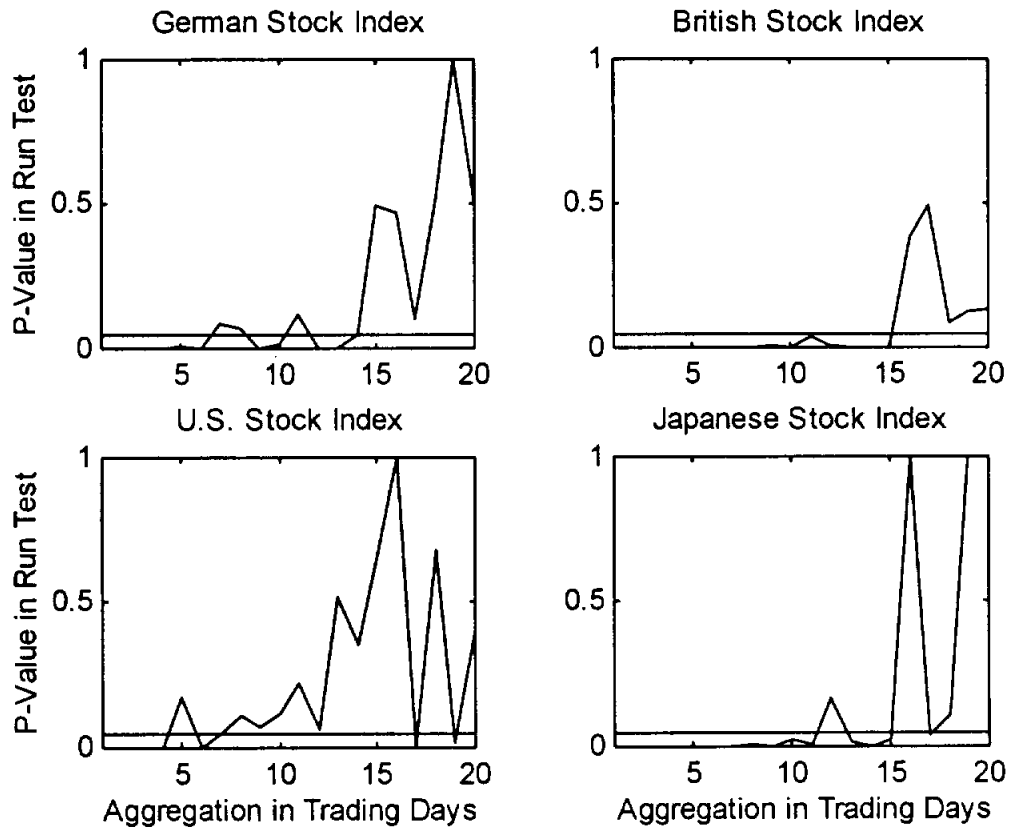
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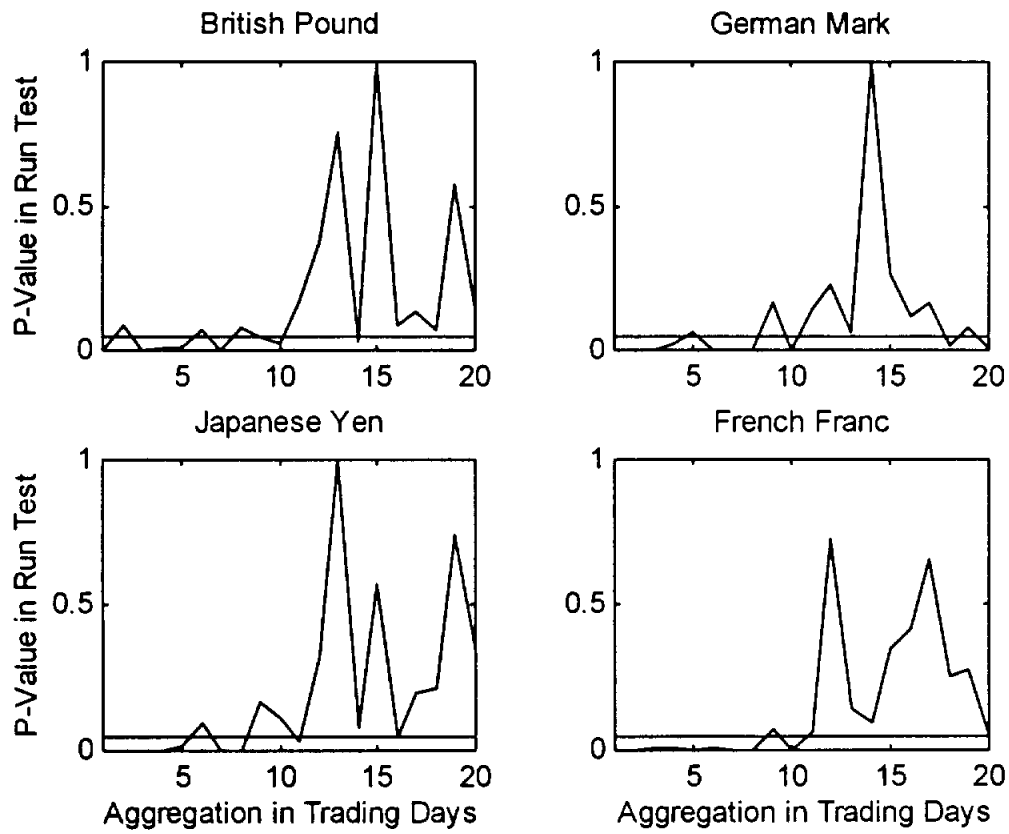
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Figure 1
P-Values of Runs Tests
Four Equity Indexes



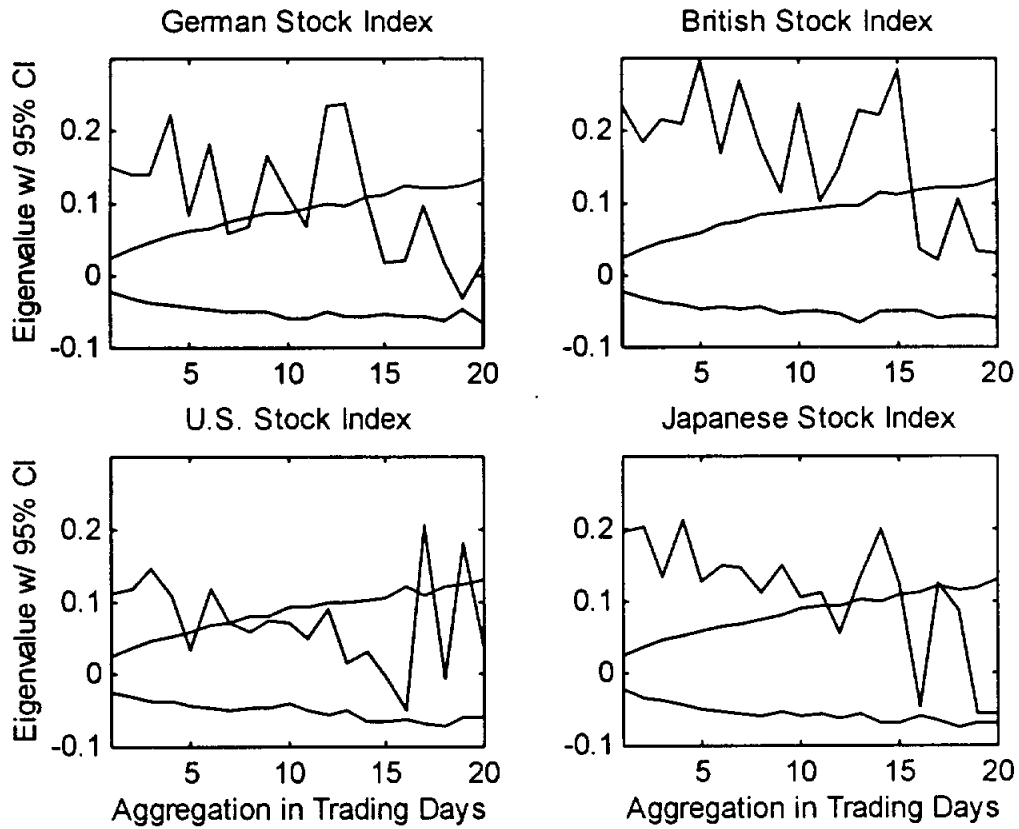
Notes to figure: For each series and horizon we plot the finite-sample P-value associated with the runs test on the hit sequence corresponding to a constant $\pm 2\hat{\sigma}$ interval forecast. The horizontal line is at 5 percent.

Figure 2
P-Values of Runs Tests
Four Dollar Exchange Rates



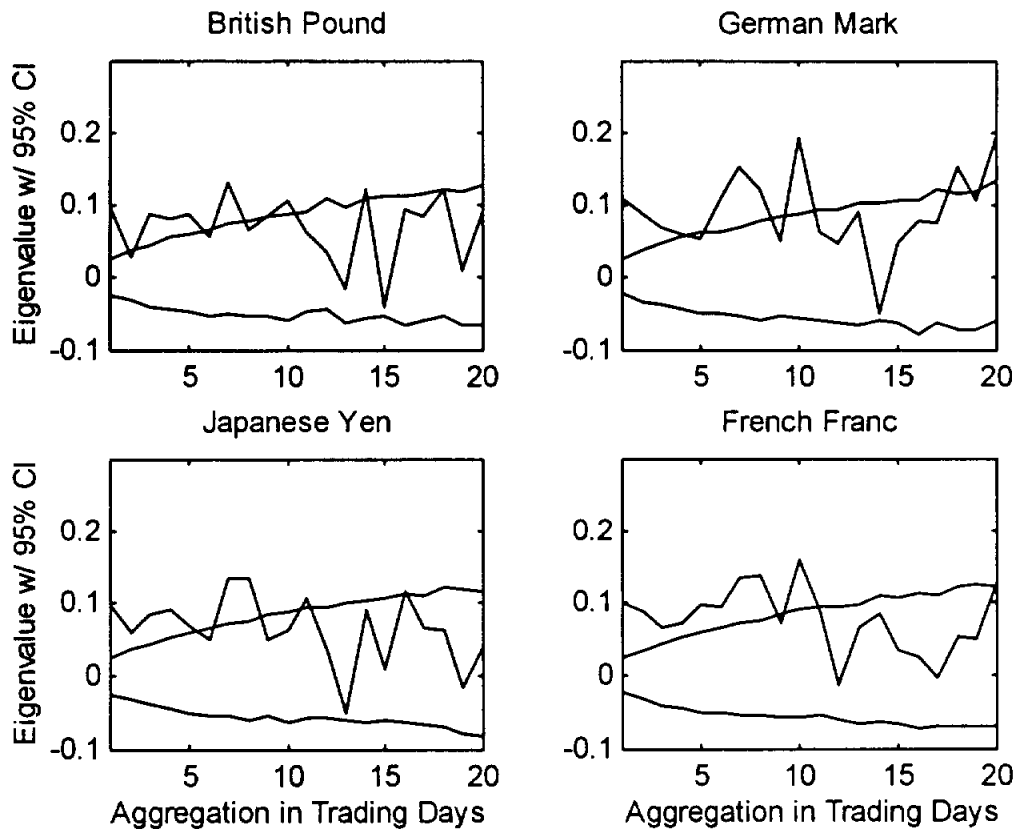
Notes to figure: For each series and each horizon we plot the finite-sample P-value associated with the runs test on the hit sequence corresponding to a constant $\pm 2\hat{\sigma}$ interval forecast. The horizontal line is at 5 percent.

Figure 3
 Markov Transition Matrix Eigenvalues
 Four Equity Indexes



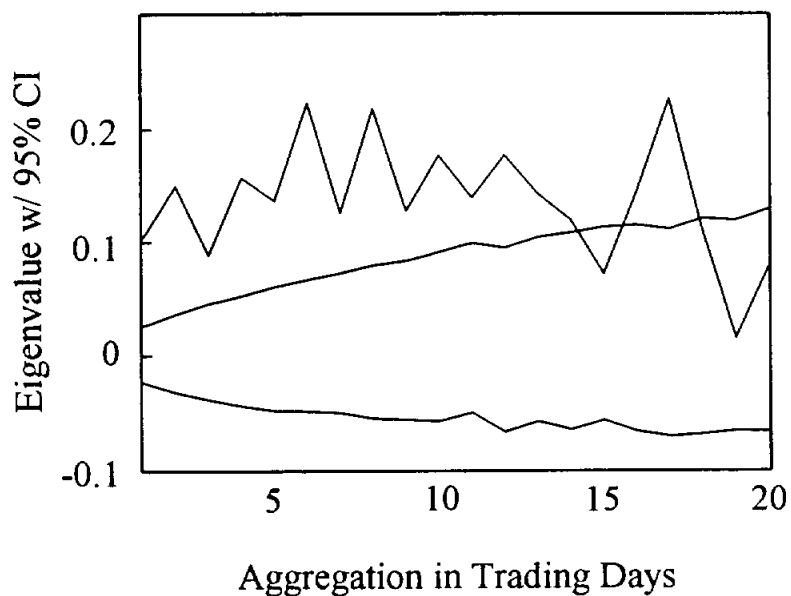
Notes to figure: For each series and each horizon we plot the estimated eigenvalue of the transition matrix estimated from the hit sequence corresponding to a constant $\pm 2\hat{\sigma}$ interval forecast, along with the finite-sample 95 percent confidence interval when the eigenvalue is zero. We construct the finite-sample confidence interval from empirical percentiles based on 4000 simulations.

Figure 4
Markov Transition Matrix Eigenvalues
Four Dollar Exchange Rates



Notes to figure: For each series and each horizon we plot the estimated eigenvalue of the transition matrix estimated from the hit sequence corresponding to a constant $\pm 2\hat{\sigma}$ interval forecast, along with the finite-sample 95 percent confidence interval when the eigenvalue is zero. We construct the finite-sample confidence interval from empirical percentiles based on 4000 simulations.

Figure 5
Markov Transition Matrix Eigenvalues
U.S. 10-Year Government Bond



Notes to figure: For each horizon we plot the estimated eigenvalue of the transition matrix estimated from the hit sequence corresponding to a constant $\pm 2\hat{\sigma}$ interval forecast, along with the finite-sample 95 percent confidence interval when the eigenvalue is zero. We construct the finite-sample confidence interval from empirical percentiles based on 4000 simulations.